

model_v1

October 15, 2023

```
[1]: import torch
from torch.utils.data import IterableDataset, DataLoader
import numpy as np
from third_party.absl_py import app
from third_party.absl_py import flags
import torch.nn as nn
import torch.nn.functional as F
from torch.utils.data import random_split
import random
import file.recordio as recordio

import projects.sc_eval.bw.bw_pb2 as bw_pb2
```

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[2]: def one_hot_race(race, num_classes):
    return [1 if i == race else 0 for i in range(num_classes)]

class BwExampleDataset(IterableDataset):
    def __init__(self, path, after_sec=0):
        self.path = path
        self.reader = recordio.RecordReader(path)
        self.after_sec = after_sec

    def __iter__(self):
        return self

    def __next__(self):
        example = None
        while True:
            message = self.reader.ReadMessage()
            if message is None:
                raise StopIteration()
            example = bw_pb2.BwExampleV1.FromString(message)
            if example.seconds >= self.after_sec:
                break
```

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        p0_actions_global = torch.tensor(example.p0_actions_global, dtype=torch.
↪float32)
        p0_actions_recent = torch.tensor(example.p0_actions_recent, dtype=torch.
↪float32)
        p1_actions_global = torch.tensor(example.p1_actions_global, dtype=torch.
↪float32)
        p1_actions_recent = torch.tensor(example.p1_actions_recent, dtype=torch.
↪float32)

        counts = torch.cat(
            [
                p0_actions_global,
                p0_actions_recent,
                p1_actions_global,
                p1_actions_recent,
            ]
        )

        normalized_counts = torch.log(counts + 1)

        p0_race_encoded = torch.tensor(
            one_hot_race(example.p0_race, 4), dtype=torch.float32
        )
        p1_race_encoded = torch.tensor(
            one_hot_race(example.p1_race, 4), dtype=torch.float32
        )

        label = torch.tensor([1, 0] if example.p0_wins else [0, 1], dtype=torch.
↪float32)

        features = torch.cat(
            [
                normalized_counts,
                p0_race_encoded,
                p1_race_encoded,
            ]
        )

        return features, label

    def Restart(self):
        self.reader.Close()
        self.reader = recordio.RecordReader(self.path)

```

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[3]: # Hyperparameters
batch_size = 512
learning_rate = 0.001
epochs = 3
```

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[4]: device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
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[5]: train_data = BwExampleDataset("/jfs/sc_eval/bw/train.recordio")
test_data = BwExampleDataset("/jfs/sc_eval/bw/test.recordio")

train_loader = DataLoader(train_data, batch_size=batch_size)
test_loader = DataLoader(test_data, batch_size=batch_size)
```

```
[6]: class SimpleClassifier(nn.Module):
    def __init__(self, input_size, hidden_size, output_size):
        super(SimpleClassifier, self).__init__()

        self.fc1 = nn.Linear(input_size, hidden_size)
        self.fc2 = nn.Linear(hidden_size, output_size)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.relu(self.fc1(x))
        x = self.fc2(x)
        return nn.functional.softmax(x, dim=1) # Apply softmax along dimension

ex = next(train_data)
input_size = ex[0].shape[0]
output_size = ex[1].shape[0]
# Common advice is that the hidden layer size should be the mean of the input +
↳output.
hidden_size = (input_size + output_size) // 2
model = SimpleClassifier(input_size=input_size, hidden_size=hidden_size,
↳output_size=output_size).to(device)
print(f"input={input_size} hidden={hidden_size} output={output_size}")
```

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input=128 hidden=65 output=2
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```
[7]: for fea, lab in test_loader:
    print(fea.shape)
    break
```

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torch.Size([512, 128])
```

```
[8]: def RunModelOnTestData(loader=test_loader, num_batches=-1):
    num_correct = num_total = 0
```

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    for features, labels in loader:
        features, labels = features.to(device), labels.to(device) # TODO:
        ↪ Maybe GPU is excessive/slower here?
        predictions = model(features).squeeze()
        _, indices = predictions.max(dim=1)
        actual_indices = torch.max(labels, 1)[1]
        num_correct += (indices == actual_indices).sum().item()
        num_total += batch_size

    if num_batches != -1:
        num_batches -= 1
    if num_batches == 0:
        break

    print(f"Test data got {num_correct} / {num_total} correct, or {num_correct}/
    ↪ num_total}")

```

```

[9]: # Run a pass through the test dataset before training to confirm there's around
    ↪ a 50% chance of getting it right.
    RunModelOnTestData(num_batches=100)

    # Loss Function and Optimizer
    criterion = nn.CrossEntropyLoss()
    optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate)

    # Training Loop
    for epoch in range(epochs):
        model.train()
        total_loss = 0
        i = 0

        # Decrease learning rate for last epoch.
        if epoch == epochs - 1:
            learning_rate *= 0.1

        for features, labels in train_loader:
            i += 1
            features, labels = features.to(device), labels.to(device)
            optimizer.zero_grad()

            # Forward pass.
            outputs = model(features)
            loss = criterion(outputs, torch.max(labels, 1)[1])
            total_loss += loss.item()

            # Backward pass and optimize.
            loss.backward()
            optimizer.step()

```

```
train_data.Restart()
test_data.Restart()

RunModelOnTestData(num_batches=100)
```

```
RunModelOnTestData()
```

```
Test data got 24317 / 51200 correct, or 0.47494140625
Test data got 30328 / 51200 correct, or 0.59234375
Test data got 30293 / 51200 correct, or 0.59166015625
Test data got 30321 / 51200 correct, or 0.59220703125
Test data got 504434 / 887296 correct, or 0.5685070145701097
```

```
[13]: test_data.Restart()
after_5_data = BwExampleDataset("/jfs/sc_eval/bw/test.recordio",
    ↪after_sec=60*20)
after_5_loader = DataLoader(test_data, batch_size=batch_size)
RunModelOnTestData(loader=after_5_loader)
```

```
Test data got 534755 / 938496 correct, or 0.5697999778368794
```

0.1 TODO:

Make a graph that looks at single replays and inspect games.